Forecasting Global Point-Rainfall

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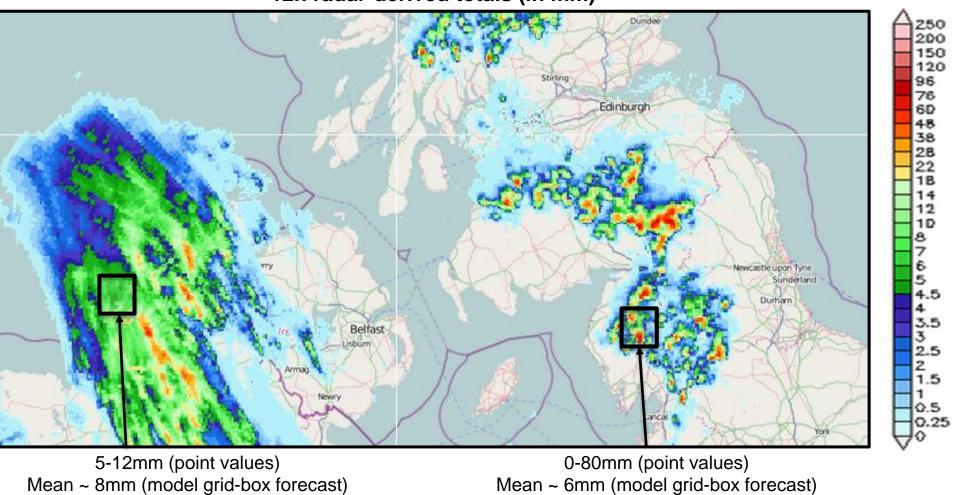
The Concept

Mostly we want to forecast extreme point-rainfall



Anticipate
different
degrees of subgrid variability
(and account for
model biases)

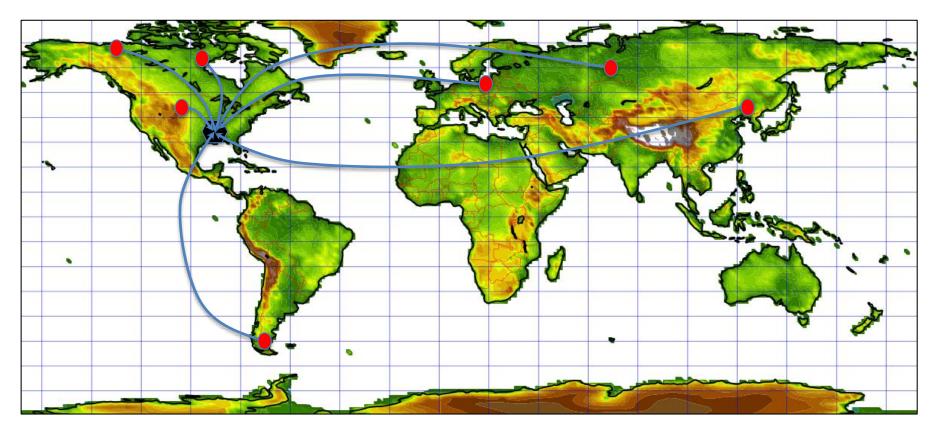
12h radar-derived totals (in mm)





The (Innovative) Approach

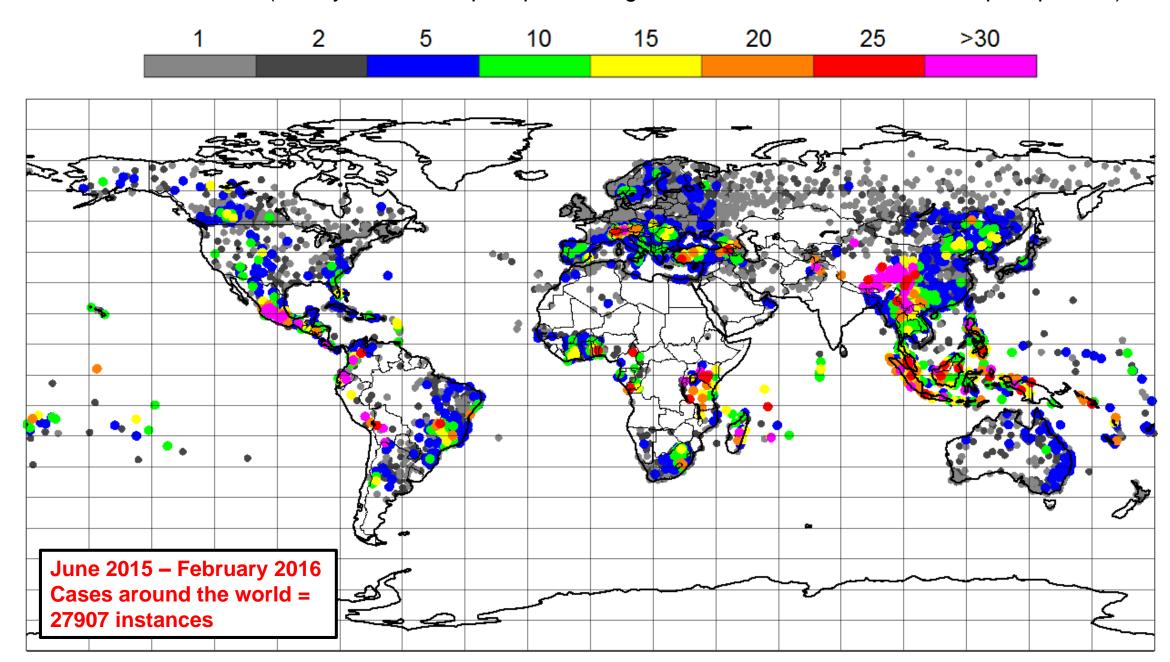
We want to forecast rainfall for, let's say Louisiana, and the conditions are: mainly convection, light winds, in summer. Then, we can pose the following question: how the model performed, at a short range, in other sites with similar conditions (relatively flat areas, similar forecast conditions)?



Errors at those sites, at those times, provide a good guide to assess the model reliability for those particular conditions and indeed, provide a pdf to post-process the ensemble member that predicted the same conditions.



Extreme Weather in UK (mainly convective precipitation, light winds, medium values of total precipitation)



The (Innovative) Approach

- Use of remote sites immediately provides a massive training dataset, from a short training period (if we use global data)
- For calibration we focus on short range forecasts, to minimize random errors
- The actual forecast itself can be for any lead time, for any gridbox
- In this way we create probabilistic forecasts for points, using global conditional verification as a means of calibrating the raw gridbox forecast

The Approach with an Ensemble

- Here one adds together (and normalizes) the pdfs created as above for each ensemble member
- Each ensemble member may of course not predict the same meteorological conditions and those would be post-processed in the same general way, but using training data for other contions (and values of other variables as relevant, and as represented in those members)

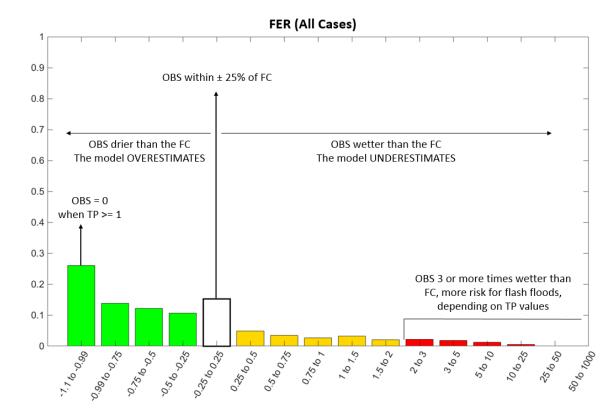


Compare O_{point} with $F_{gridCAL}$ (where tp>=1) over all available cases

to determine

Forecast Error Ratio $FER = \frac{O_{point} - FgridCA_{L}}{F_{gridCAL}}$

A probability density function (pdf) for all FER, $\Omega(FER)$, can be generated. It is called **Mapping Function**.





The efficacy/utility of this procedure Creation of Multiple Mapping Functions for n physically & significantly different Weather Types (WTs) to capture sub-grid variability within the model grid-box and model biases.

Predictors to create the WTs

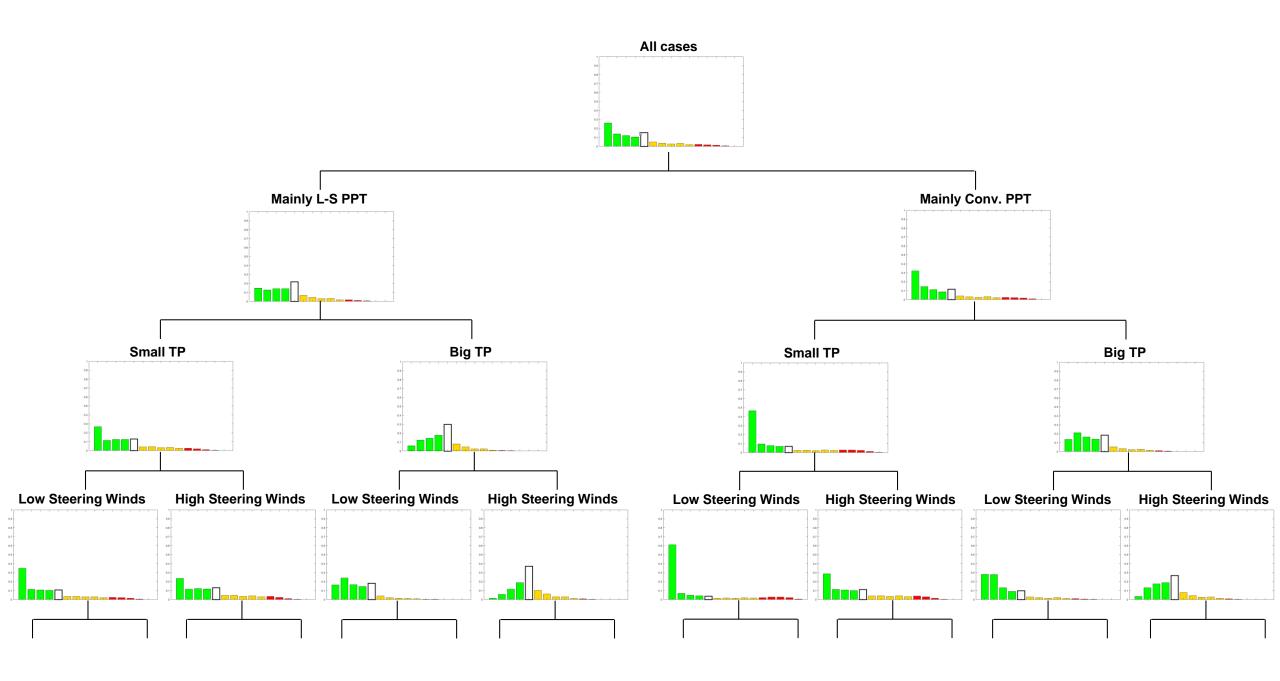
(= geographical / solar / raw model / derived parameters)

Current pre-operational version

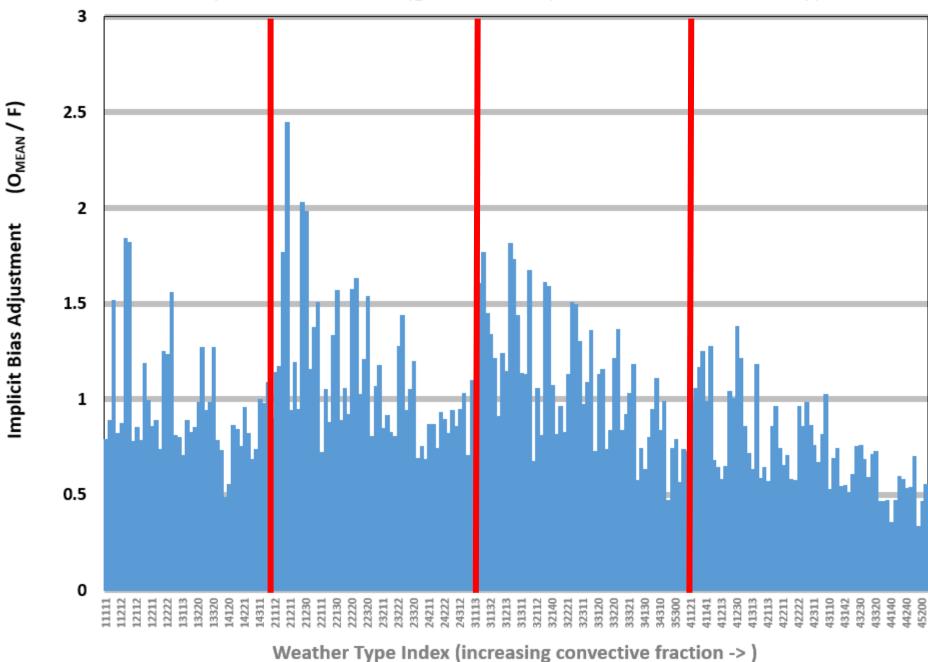
- Convective Precipitation Fraction
 - Total precipitation forecast
- Mean speed (in period) of steering winds at 700 mbar
 - · Convective available potential energy
 - Clear Sky solar radiation, 24h accumulation

Future Research

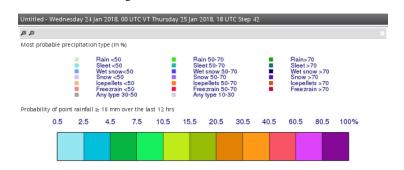
- Complex orographic areas
 - Coastal areas
- Rural and Urban areas
- Day, night, polar night
 - Cloud cover
- Boundary layer depth
 - Etc

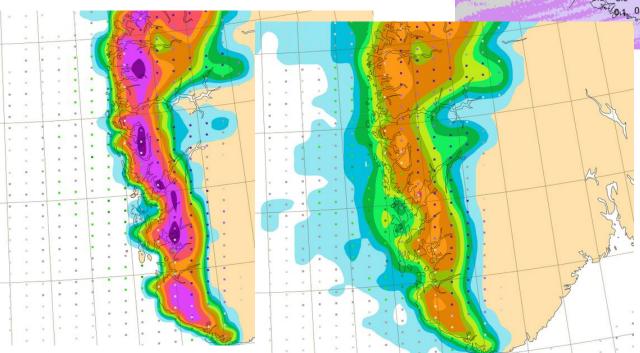


Implied Mean "Bias" (gridbox scale) for different Weather Types



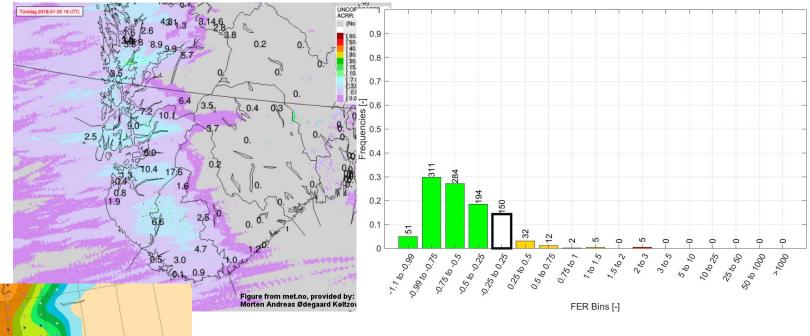
ExampleNorway, 25/01/2018, 00 UTC

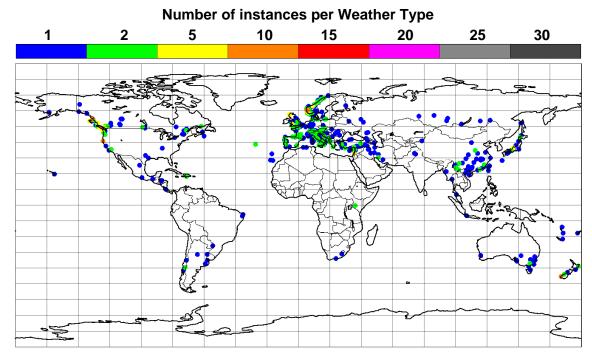




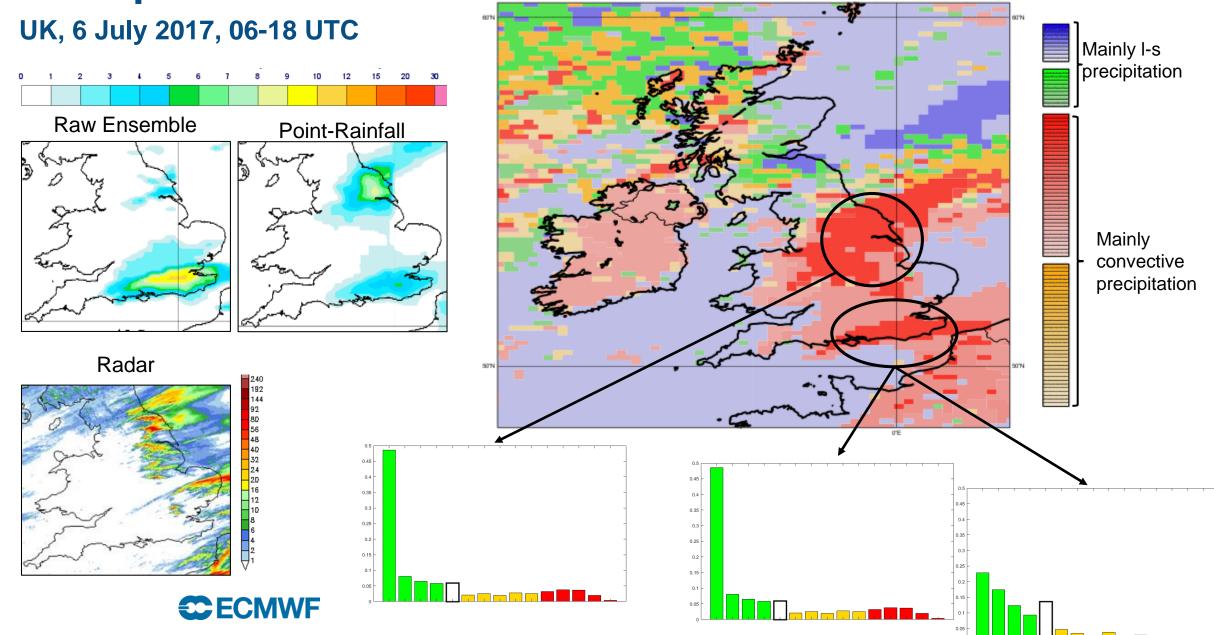
12hr_accumulated_precip_20180125_18UTC.png







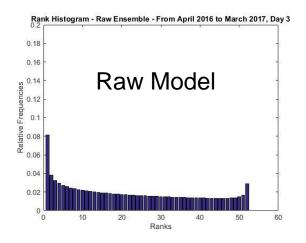
Example

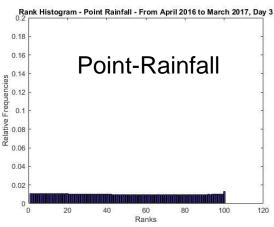


VERIFICATION

Long-term verification (April 2016 – March 2017) & different lead times (Day 1, 3, 5)

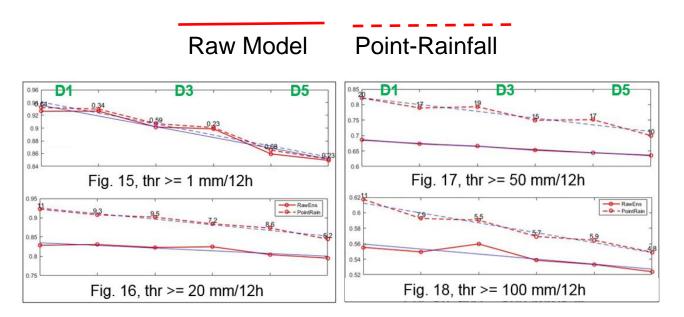
Reliability (Rank Histograms)







Resolution Component (Area under the ROC curve)



By this metric, for "large" totals the Point Rain product is ~ as skilful at day 5 as the Raw ENS is at day 1

=> Much better probabilistic flash flood predictions