In this lecture we will give you a brief history of ECMWF and present the main areas of NWP research that is currently being carried out in the centre. We then look at current research challenges and present some of the latest developments that will soon become operational.

By the end of the lecture you should be able to:

- List the main research areas at ECMWF and describe the latest model developments.

Erland Källén, Sarah Keeley

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<th>Time</th>
<th>Monday</th>
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<tr>
<td>9:15</td>
<td>In this lecture we will give you a brief history of ECMWF and present the main areas of NWP research that is currently being carried out in the centre. We then look at current research challenges and present some of the latest developments that will soon become operational.</td>
<td>Mike Fisher</td>
<td>Mike Fisher</td>
</tr>
</tbody>
</table>
The aim of these sessions is to understand the role of land surface data assimilation on medium range weather forecasts.

We will give an overview of the different approaches used to assimilate land surface data and to initialise model variables in NWP. We will present the current observing systems and describe the land data assimilation structure within ECMWF system.

By the end of the session you should be able to:
- identify the different observations used for snow and soil moisture data assimilation
- define land surface data assimilation approaches used for NWP
- describe the role of land surface data assimilation on medium-range weather forecasts

Patricia de Rosnay

The Ensemble of Data Assimilation (EDA) technique is used for the estimation of the analysis and background errors of the ECMWF assimilation system. This lecture describes the EDA formulation and implementation, and how it interacts with ECMWF 4DVar analysis and ECMWF Ensemble Prediction System.

By the end of the lecture the participants should be able to:
- Describe the theoretical basis and practical implementation of the EDA
- Explain the use of the EDA in the ECMWF analysis and ensemble prediction systems

Massimo Bonavita
11.45

The aim of this session is to present an overview of the current observing systems used in Numerical Weather Prediction. We will discuss our observational requirement, and how close the current observing system is to meeting our needs. We will also discuss areas where our requirements are evolving. We will learn about WMO's OSCAR database that describes the Global Observing System. We will learn how the large diversity of observations now available, are monitored to ensure only good observations are presented to an operational system.

By the end of the session you should be able to:
- be able to describe the main types of observations used in data assimilation for Numerical Weather Prediction;
- be aware of how large volumes of observations are exchanged, implemented and monitored in operational systems;
- be aware of WMO's OSCAR database, how to access it and what type of information it can provide.

Steve English

---

The background error is central to the performance of the analysis system and tells how much confidence to put in the best available forecast which is to be updated with new observations. The lecture will review how background errors are estimated and represented for current variational algorithms.

Elias Holm

---

The aim of this lecture is to introduce the concept of the EnKF in the context of atmospheric data assimilation. Strengths and weaknesses of the algorithm will be discussed and results of the ECMWF implementation will be presented.

By the end of the lecture the participants should be able to:
- describe the basic EnKF algorithm and its connections with the Kalman Filter;
- discuss some of the advantages and limitations of EnKF algorithms with respect to more established variational algorithms;
- be aware of recent developments in hybrid variational-EnKF data assimilation.

Massimo Bonavita
In this lecture the variational bias correction scheme (VarBC) as used at ECMWF is explained. VarBC replaced the tedious job of estimating observation bias off-line for each satellite instrument or in-situ network by an automatic self-adaptive system. This is achieved by making the bias estimation an integral part of the ECMWF variational data assimilation system, where now both the initial model state and observation bias estimates are updated simultaneously.

By the end of the session you should be able to realize that:
- many observations are biased, and that the characteristics of bias varies widely between types of instruments
- separation between model bias and observation bias is often difficult
- the success of an adaptive system implicitly relies on a redundancy in the underlying observing system.

Dick Dee

The goal of this lecture is to familiarise the student with the notion of tangent linear and adjoint models, and their use in variational data assimilation. A general overview of the current use of tangent linear and adjoint models in the ECMWF system will also be provided. Theoretical definitions and practical examples of tangent linear and adjoint models will be given. The student will be invited to work some simple tangent linear and adjoint derivations together with the instructor. A brief introduction to automatic differentiation software will also be given.

By the end of the session you should be able to:
- define what tangent linear and adjoint models are
- derive tangent linear and adjoint equations for a simple nonlinear equation
- describe the use of tangent linear and adjoint codes within the ECMWF's 4D-VAR system.

Toy Model Practice Session (1)
Mike Fisher, Yannick Tremolet, Martin Leutbecher

OR

Angela Benedetti
The aim of these sessions is to understand the role of land surface data assimilation on medium range weather forecasts.

We will give an overview of the different approaches used to assimilate land surface data and to initialise model variables in NWP. We will present the current observing systems and describe the land data assimilation structure within ECMWF system.

By the end of the session you should be able to:

- identify the different observations used for snow and soil moisture data assimilation
- define land surface data assimilation approaches used for NWP
- describe the role of land surface data assimilation on medium-range weather forecasts

Patricia de Rosnay

A single observation can under some conditions undermine the quality of a global analysis. The lecture will go through methods used to make the analysis more robust against outlier or wrong observations, with focus on variational quality control.

Elias Holm

Followed by drinks reception and poster session

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<th>Time</th>
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<tr>
<td>9:30 - 10:45</td>
<td>Meet the students</td>
<td>The infrared spectrum- measurement, modelling and information content</td>
<td>GPS Radio Occulation: Extended applications</td>
<td>Observation errors for satellite data assimilation</td>
<td>Satellites for environmental monitoring and forecasting</td>
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<td></td>
<td>Tony McNally</td>
<td>Tony McNally</td>
<td>Sean Healy GPSRO_lecture2_2016_nwpsaf.ppt</td>
<td>Niels Bormann ObsErrors_2016.ppt</td>
<td>Richard Engelen NWP_SAF_Engelen.pptx</td>
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<tr>
<td>11:15 - 12:30</td>
<td>Theoretical background (1) What do satellites measure ? Tony McNally</td>
<td>GPS Radio Occulation: Principles and NWP use Sean Healy</td>
<td>The detection and assimilation of clouds in infrared radiances Tony McNally</td>
<td>Background errors for satellite data assimilation Tony McNally</td>
<td>Mohamed Dahoui Dahoui_Satellite_2016.pptx</td>
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<td></td>
<td>SAT_TC_What_do_Satellites_Measure_TM.ppt</td>
<td>SAT_TC_What_do_Satellites_Measure_TM.ppt</td>
<td>SAT_TC_Detection_and_assimilation_clouds_IR.ppt</td>
<td>SAT_TC_Background_errors_TM.ppt</td>
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<tr>
<td>14:00 - 15:15</td>
<td>Theoretical background (2) Data assimilation algorithms, Key elements and inputs Tony McNally</td>
<td>Satellite information on the ocean surface (SCAT) Giovanna De Chiara</td>
<td>The detection and assimilation of clouds and rain in microwave radiances Alan Geer</td>
<td>Satellite information on the land surface Patricia de Rosnay</td>
<td>Current satellite observing network and its future evolution Stephen English CurrentAndFutureSatellite.pptx</td>
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<td>SAT_TC_Data_assimilation_key_elements_TM.ppt</td>
<td>training_course_2016_GDC_no_notes.ppt</td>
<td>sat_microwave_2016_2.ppt</td>
<td>Land_satellite_NWP_SAF.ppt</td>
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<tr>
<td>15:45 - 17:00</td>
<td>The microwave spectrum, measurement, modelling and information content Alan Geer</td>
<td>A Practical guide to IR and MW radiative transfer – using the RTTOV model and GUI</td>
<td>Wind information from satellites (Atmospheric Motion Vectors) Katie Lean</td>
<td>1DVar theory, simulator + practical session on background and observation errors Tony McNally</td>
<td>Question and answer session, course evaluation</td>
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<td>sat_microwave_2016_1.ppt</td>
<td>SAT_RT_modelling_lecture_JAH.ppt/SAT_RT_modelling_practical_JAH.ppt</td>
<td>SAT_RT_modelling_practical_JAH.ppt</td>
<td>SAT_TC_1DVAR_practical.ppt</td>
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<td>Introductions</td>
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By the end of the session you should be able to:

- describe some important aspects of the formulation and implementation of the governing equations in generalised coordinates
- describe various vertical coordinates employed in atmospheric models
- indicate the use of generalised coordinates to employ moving mesh adaptivity

**Christian Kühnlein**

During this presentation, we will discuss two of the questions faced by numerical weather prediction scientists as forecast models reach horizontal resolutions of 6 to 2 km:

- Do we need to abandon the primitive equations for a non-hydrostatic system of equations?
- Do we still need a deep convection parametrisation?
- and we will show what answers to these questions are given by very high resolution simulations of the IFS.

By the end of the presentation, you should be able to:

- discuss the limits of the hydrostatic approximation for numerical weather prediction
- explain the dilemma of parametrizing deep convection versus permitting explicit deep convection at resolution in the grey zone of convection

**Sylvie Malardel**

The aim of this lecture is to systematically build theoretical foundations for Numerical Weather Prediction at non-hydrostatic resolutions. In the first part of the lecture, we will discuss a suite of all-scale non-hydrostatic PDEs, including the anelastic, the pseudo-incompressible and the fully compressible Euler equations of atmospheric dynamics. First we will introduce the three sets of nonhydrostatic governing equations written in a physically intuitive Cartesian vector form, in abstraction from the model geometry and the coordinate frame adopted. Then, we will combine the three sets into a single set recast in a form of the conservation laws consistent with the problem geometry and the unified solution procedure. In the second part of the lecture, we will build and document the common numerical algorithm for integrating the generalised set of the governing PDEs put forward in the first part of the lecture. Then, we will compare soundproof and compressible solutions and demonstrate the efficacy of this unified numerical framework for nes idealised flow problems relevant to weather and climate.

By the end of the lecture you should be able to:

- explain the form, properties and role of alternative systems of non-hydrostatic PDEs for all scale atmospheric dynamics;
- explain the importance and key aspects of continuous mappings employed in all-scale atmospheric models;
- explain the difference between the explicit and semi-implicit algorithms for integrating nonhydrostatic-PDEs, the importance of consistent numerical approximations, and the fundamental role of transport and elliptic solvers.

**Piotr Smolarkiewicz**

Course2016_smolar.pdf

The aim of this session is to learn about recent developments in discontinuous higher order spatial discretization methods, such as the Discontinuous Galerkin method (DG), and the Spectral Difference method (SD). These methods are of interest because they can be used on unstructured meshes and facilitate optimal parallel efficiency. We will present an overview of higher order grid point methods for discretizing partial differential equations (PDEs) with compact stencil support, and illustrate a practical implementation.

By the end of the session you should be able to:

- all the advantages offered by discontinuous higher order methods
- describe how to solve PDE's with discontinuous methods
- identify the key elements that contribute to a PDE solver

**Willem Deconinck**
<table>
<thead>
<tr>
<th>Time</th>
<th>Session Title</th>
<th>Speaker</th>
<th>PPTX Link</th>
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| 10:35 | Using the 30-year history of ECMWF’s Integrated Forecasting System (IFS) as an example, this lecture is an introduction to the development and current state-of-the-art of global numerical weather prediction (NWP), as well as to the challenges faced in the future. It is intended to provide an overview and context for the topics covered in more detail during the course. By the end of the session you should be able to:  
- describe the development of global NWP, the current state-of-the-art, and future challenges  
- identify relevant areas of research in numerical methods for Earth System Modelling  
- put into context every subsequence lecture and its purpose | Christian Kühnlein                  | kuehnlein_EC_TC2016_W.pdf |
|       | Practical Session                                                             | Willem Deconinck, Christian Kühnlein | Practical_Session_Lecture_1_wedi.pptx               |
|       | The aim of this lecture is to systematically build theoretical foundations for Numerical Weather Prediction at nonhydrostatic resolutions. In the first part of the lecture, we will discuss a suite of all-scale nonhydrostatic PDEs, including the anelastic, the pseudo-incompressible and the fully compressible Euler equations of atmospheric dynamics. First we will introduce the three sets of nonhydrostatic governing equations written in a physically intuitive Cartesian vector form, in abstraction from the model geometry and the coordinate frame adopted. Then, we will combine the three sets into a single set recast in a form of the conservation laws consistent with the problem geometry and the unified solution procedure. In the second part of the lecture, we will build and document the common numerical algorithm for integrating the generalised set of the governing PDEs put forward in the first part of the lecture. Then, we will compare soundproof and compressible solutions and demonstrate the efficacy of this unified numerical framework for two idealised flow problems relevant to weather and climate. By the end of the lecture, you should be able to:  
- explain the form, properties and role of alternative systems of nonhydrostatic PDEs for all-scale atmospheric dynamics  
- explain the importance and key aspects of continuous mappings employed in all-scale atmospheric models  
- explain the difference between the explicit and semi-implicit algorithms for integrating nonhydrostatic PDEs, the importance of consistent numerical approximations, and the fundamental role of transport and elliptic solvers | Piotr Smolarkiewicz | Smolarkiewicz_EC_TC2016_W.pdf |
|       | The aim of this session is to learn about recent developments in discontinuous higher order spatial discretization methods, such as the Discontinuous Galerkin method (DG), and the Spectral Difference method (SD). These methods are of interest because they can be used on unstructured meshes and facilitate optimal parallel efficiency. We will present an overview of higher order grid point methods for discretizing partial differential equations (PDEs) with compact stencil support, and illustrate a practical implementation. By the end of the session, you should be able to:  
- explain what are the advantages offered by discontinuous higher order methods  
- describe how to solve PDEs with discontinuous methods  
- identify the key elements that contribute to a PDE solver | Willem Deconinck | Deconinck_EC_TC2016_W.pdf |
The success of the spectral transform method in global NWP in comparison to alternative methods has been overwhelming, with many operational forecast centres (including ECMWF) having made the spectral transform their method of choice. The lecture will introduce the basic elements of the spectral transform, explain why it has been successful and describe recent developments such as the fast Legendre transform. By the end of the session you should be able to:

- explain what the spectral transform method is, how it is applied, and describe the latest developments at ECMWF;
- give reasons why it is successful for global NWP and climate;
- identify potential advantages and disadvantages of the method.

Nils Wedi
Lecture_2_wedi.pptx

### Practical Session

Willem Deconinck, Christian Köhlein

Recently, there is increasing interest in trying to understand the properties of coupled atmosphere, ocean-wave, ocean/sea-ice models with an ultimate goal to start predicting weather, waves and ocean circulation on time scales ranging from the medium-range to seasonal timescales. Such a coupled system not only requires the development of an efficient coupled forecasting system but also the development of a data assimilation component.

During the two lectures I will briefly describe the components of the coupled system. It will be made plausible that ocean waves are an essential element of such a coupled system as through the wave action, momentum and heat are transferred from atmosphere to ocean. Also, the sea state determines to a considerable extent the efficiency with which momentum is transferred from atmosphere to waves, while ocean waves also play a decisive role in the evolution of the sea-ice edge. Results showing the importance of ocean waves on upper-ocean mixing and on atmospheric circulation are discussed as well, while I will finish the lectures by presenting preliminary results from coupled data assimilation experiments.

By the end of this session, the student will be able to:

- discuss the impact of ocean waves on the coupled system;
- describe the different wave processes that are modelled in the ECMWF system;
- describe the impact of ocean circulation on the atmosphere.

Jean Bidlot
Advance_numerical_method_for_earth_modeling_Jean_Bidlot.pptx

The aim of this session is to understand the main issues and challenges in parallel computing, and how parallel computers are programmed today.

By the end of this session you should be able to:

- explain the difference between shared and distributed memory;
- describe the key architectural features of a supercomputer;
- describe the purpose of OpenMP and MPI on today’s supercomputers;
- identify the reasons for the use of accelerator technology.

George Mozdzynski
Massively_Parallel_Computing.pdf

### Course wrap up and Certificates

- 14.00
The aim of this session is to describe the numerical technique used in the ECMWF model for integrating the transport equations of the hydrostatic primitive equation set. We will present an overview of the semi-Lagrangian method and how it is combined with semi-implicit time-stepping to provide a stable and accurate formulation for the ECMWF Integrated Forecasting System (IFS).

By the end of this session you should be able to:

- describe the fundamental concepts of semi-Lagrangian advection schemes, their strengths and weaknesses.
- describe semi-implicit time-stepping and its use in IFS.
- explain the important role these two techniques play for the efficiency of the current IFS system.

Jean Bidlot

Recently, there is an increasing interest in trying to understand the properties of coupled atmosphere, ocean-wave, ocean/sea-ice models with an ultimate goal to start predicting weather, waves and ocean circulation on time scales ranging from the medium-range to seasonal timescale. Such a coupled system not only requires the development of an efficient coupled forecasting system but also the development of a data assimilation component.

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By the end of this session, the student will be able to:

- discuss the impact of ocean waves on the coupled system.
- describe the different wave processes that are modelled in the ECMWF system.
- describe the impact of ocean circulation on the atmosphere.

Jean Bidlot

The aim of two lectures is to introduce basis of finite volume and continuous finite element discretisations and relate them to corresponding data structures and mesh generation techniques. The main focus will be on unstructured meshes and their application to global and local atmospheric models. Flexibility, communication overheads, memory requirements and user friendliness of such meshes will be contrasted with those of structured meshes. The most commonly used mesh generation techniques will be highlighted, together with mesh manipulation techniques employed in mesh adaptation approaches and will be followed by a discussion of alternative geometrical representations of orography. An example of unstructured meshes’ implementation to non-hydrostatic and hydrostatic atmospheric solvers will provide an illustration of their potential and challenges.

By the end of the lecture you should be able to:

- understand applicability, advantages and disadvantages of selected mesh generation techniques for a given type of application.
- appreciate importance of data structures in relation to atmospheric models and mesh generation.
- gain awareness of issues related to flexible mesh generation and adaption.

Joanna Szmelter

The aim of this session is to understand the main issues and challenges in parallel computing, and how parallel computers are programmed today.

By the end of this session you should be able to:

- explain the difference between shared and distributed memory.
- describe the key architectural features of a supercomputer.
- describe the purpose of OpenMP and MPI on today’s supercomputers.
- identify the reasons for the use of accelerator technology.

George Mozdzynski
• explain the impact that future supercomputing architectures may have in the applicability of the semi-Lagrangian technique in high resolution non-hydrostatic global NWP systems.

Michail Diamantakis
SLSI.pptx

15:30
During this presentation, we will discuss two of the questions faced by numerical weather prediction scientists as forecast models reach horizontal resolutions of 6 to 2 km:

- Do we need to abandon the primitive equations for a non-hydrostatic system of equations?
- Do we still need a deep convection parametrisation?
- and we will show what answers to these questions are given by very high resolution simulations of the IFS.

By the end of the presentation, you should be able to:

- discuss the limits of the hydrostatic approximation for numerical weather prediction
- explain the dilemma of parametrizing deep convection versus permitting explicit deep convection at resolution in the grey zone of convection

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Joanna Szmelter
resolution.pdf
Sylvie Malardel
PDC_grey.pdf

In this lecture we will give you a brief history of ECMWF and present the main areas of NWP research that is currently being carried out in the centre. We then look at current research challenges and present some of the latest developments that will soon become operational.

By the end of the lecture you should be able to:

- List the main research areas at ECMWF and describe the latest model developments.

Sarah Keeley and Erland Källén
ECMWF-Past-FutureNM_2016_EK.pptx
The aim of this session is to describe alternative (to the semi-Lagrangian) numerical techniques for integrating the transport equation sets encountered in NWP models. We will present an overview of different Eulerian time-stepping techniques and discuss the advantages and disadvantages of each approach.

By the end of the session you should be able to:

- recognize the basic differences between semi-Lagrangian and Eulerian approaches
- describe the strengths and weaknesses of different time-stepping approaches such as split-explicit time-stepping, Runge-Kutta time-stepping
- describe the basic features of different time-stepping schemes used in other weather forecasting models such as WRF, ICON
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| **Introduction to the course**  
Erland Källén / Students | This session describes the representation of subgrid-scale variability of humidity, cloud and precipitation and how this can be parametrized in atmospheric models.  
By the end of the session you should be able to:  
• recognise the reasons for representing the subgrid variability of humidity and cloud in an atmospheric model  
• explain how the key quantity of cloud fraction is related to subgrid heterogeneity assumptions  
• describe the different types of subgrid cloud parametrization schemes.  
Richard Forbes  
TC2016_Forbes_L2_cloud_colphase.pptx | This session will have two mains components:  
• An overview of the role of snow in the climate system from observations, models and forecasts.  
• Description of the current representation of snow in the ECMWF model, evaluation examples and ongoing developments.  
By the end of the session, the students should be able:  
• identify the main processes associated with snow in the climate system  
• describe the main components of the snow scheme in the ECMWF model  
Emanuel Dutra  
pa_surf_2_cold_20160518.pptx | By the end of the session, the students should be able:  
• relate flux and storage  
• recognise land surface predictors and land diagnostic quantities  
Gianpaolo Balsamo  
surf2.pptx | This three-hour lecture will start by explaining the role and main ingredients of data assimilation in general. The widely used framework of variational data assimilation will then be gradually introduced. The challenges associated with the necessary inclusion of physical parametrizations in the data assimilation process will be highlighted. The concept of adjoint model as well as the techniques to derive it will be introduced. The importance of the linearity constraint in 4D-Var and the methods to address it will be detailed. The set of linearized physical parametrizations used at ECMWF will then be briefly presented. Finally, various examples of the use of physical parametrizations in variational data assimilation and its impact on weather forecast quality will be given.  
By the end of the session, the students should be able:  
• to name the main ingredients of a data assimilation system.  
• to tell why physical parametrizations are needed in data assimilation.  
• to identify the role of the adjoint code in 4D-Var.  
• to recognize the importance of the regularization of the linearized code.  
Philippe Lopez  
TC_PA_lopez_2016_main.ppt |
This module aims to introduce the fundamentals of radiative transfer theory and its role within the global atmospheric circulation. The lectures will also cover the techniques of numerical modelling of the radiative transfer equations in global-circulation models with a particular focus on the code in use in the ECMWF Integrated Forecasting System.

By the end of the session students should be able to:

• Identify the key processes controlling the atmospheric radiative balance
• Recognize the role of the radiative transfer in the Earth energy balance
• Estimate the impact of changes in the radiative parameterizations on climate

Additional outcomes:

• Develop skills in data analysis and numerical modelling

Robin Hogan
hogan_ecmwf_radiation_lecture1.pptx

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Additional outcomes:

• Develop skills in data analysis and numerical modelling

Robin Hogan
hogan_ecmwf_radiation_lecture2.pptx

Convection affects all atmospheric scales. Therefore, the convection session aims to provide a deeper understanding of the atmospheric general circulation and its interaction with convective heating and vertical transports. The notions and techniques acquired during the course should be useful for developers of convective parametrizations, forecasters and for analysing output from high-resolution convection resolving models.

By the end of the session you should become familiarised with:

• the interaction between the large-scale circulation and the convection including radiative-convective equilibrium and convectively-coupled large-scale waves
• the notion of convective adjustment and the mass flux concept in particular
• the basic concepts behind the ECMWF convection parametrization and some useful numerical tricks
• forecasting convection including convective systems and the diurnal cycle
• diagnose forecast errors related to convection.

Peter Bechtold
CONVECTION_T3_2016.ppt

This short lecture is an introduction to the questions of time splitting and process splitting in a numerical weather prediction model and to the problems resulting from the interaction of different numerical solvers inside the same model.

After this introduction, you should

• be fully aware that each parametrisation is only a small part of a much larger system, usually one term in the full system of equations which needs to be solved by the forecast model,
• remember, when working on your own parametrisation(s), that parametrisations are also subject to the constraints imposed by numerical analysis and algorithmic, as is the solver in the dynamical core.

Sylvie Malardel
PDC_2016.pdf
This session gives a theoretical introduction to the planetary boundary layer, including its definition, classification, notions about turbulence within the boundary layer, differences between clear and cloudy boundary layers, and equations used to describe the mean airflow in a numerical model.

**Expected outcomes:**
- understand what is the boundary layer, its characteristics and why it is important to study it and represent it correctly in numerical models
- understand the difference between the various boundary layer types

Irina Sandu

| pb1_is_2016.pdf |

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By the end of the session students should be able to:
- identify the key processes controlling the atmospheric radiative balance
- recognize the role of the radiative transfer in the Earth energy balance
- estimate the impact of changes in the radiative parameterizations on climate

**Additional outcomes:**
- develop skills in data analysis and numerical modelling

Alessio Bozzo

Bozzo_Radiation_Lecture3.pptx

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- the notion of convective adjustment and the mass flux concept in particular
- the basic concepts behind the ECMWF convection parameterization and some useful numerical tricks
- forecasting convection including convective systems and the diurnal cycle
- diagnose forecast errors related to convection.

Peter Bechtold

CONVECTION_T2_2016.ppt

Building on the previous two Cloud sessions, the practical implementation of a cloud parametrization is described, using the ECMWF global model as an example appropriate for global weather forecasting.

By the end of the session you should be able to:
- explain the key sources and sinks of cloud and precipitation required in a parametrization
- describe the main components of the ECMWF stratiform cloud parametrization
- recognise the limitations of approximating complex processes.

Richard Forbes

TC2016_Forbes_L3_cloud_subgrid.pptx

This session gives an overview of techniques and data sources used for the verification of the boundary layer scheme. We will use examples from the IFS to explore how verification methods can help to identify systematic errors in the model’s boundary layer parameterization, and guide future model development.

By the end of this session you should be able to:
- identify data sources and products suitable for BL verification
- recognize the strengths and limitations of the verification strategies discussed
- choose a suitable verification method to investigate model errors in boundary layer height, transport and cloudiness.

Maike Ahlgrimm

CldPblVeri2016.ppt

This session gives a brief overview of cloud parametrization issues and an understanding of the basic microphysics of liquid, ice and mixed phase cloud and precipitation processes.

By the end of the session you should be able to:
- recall the basic concepts for the design of a cloud parametrization
- describe the key microphysical processes in the atmosphere
- recognize the important microphysical processes that need to be parametrized in a global NWP model.

Richard Forbes

TC2016_Forbes_L1_cloud_warmphase.pptx

This session focuses on the parameterization of the surface layer, i.e. the layer between the surface and the first model level. More particularly, it explains how the surface fluxes are parametrized, and it gives insights on the representation of the surfaces roughness lengths which are one of the crucial aspects of the formulation of the surface fluxes.

**Expected outcomes:**
- be aware of the difficulties related to the representation of the surface layer in a numerical model
- understand how the surface fluxes are parametrized

Irina Sandu

pb2_is_new.pdf

This three-hour lecture will start by explaining the role and main ingredients of data assimilation in general. The widely used framework of variational data assimilation will then be briefly introduced. The challenges associated with the necessary inclusion of physical parametrizations in the data assimilation process will be highlighted. The concept of adjoint model as well as the techniques to derive it will be introduced. The importance of the linearity constraint in 4D-Var and the methods to address it will be detailed. The set of linearized physical parameterizations used at ECMWF will then be briefly presented. Finally, various examples of the use of physical parametrizations in variational data assimilation and its impact on weather forecast quality will be given.

By the end of the session, the students should be able to:
- name the main ingredients of a data assimilation system.
- tell why physical parametrizations are needed in data assimilation.
- identify the role of the adjoint code in 4D-Var.
- recognize the importance of the regularization of the linearized code.

Philippe Lopez

subgrid_orography_2016.ppt
### By the end of the session students should be able to:
- recognise land elements relevant to weather,
- review land modelling strategies to heterogeneity

### Gianpaolo Balsamo
- Introduction to the Single Column Model
  - Filip Vana
  - Lecture2016.pdf
- Land Surface exercises
  - Gianpaolo Balsama and Emanuel Dutra
- Boundary Layer & Cloud exercises
  - Irina Sandu, Mairke Ahlgrimm and Richard Forbes

### Moist Processes Games
- Radiation exercises
  - Alessio Bozzo and Robin Hogan
- Land Surface exercises
  - Gianpaolo Balsama and Emanuel Dutra
- Boundary Layer & Cloud exercises
  - Irina Sandu, Mairke Ahlgrimm and Richard Forbes

### Time:

<table>
<thead>
<tr>
<th>Monday</th>
<th>Tuesday</th>
<th>Wednesday</th>
<th>Thursday</th>
<th>Friday</th>
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</thead>
</table>
| 9:15-10:15 | Introduction to the course with Computer Hall tour | In this session the generation of the perturbed initial condition of the ECMWF ensemble will be presented. We will discuss the ratio behind using singular vectors in the ensemble and how they are calculated. Then it will be explained how the singular vectors are combined with perturbations from the ensemble of data assimilations to construct the perturbations for the ensemble.

By the end of the session you should be able to:
- explain the idea behind using singular vectors in the ensemble
- describe how singular vectors are calculated
- describe the construction of the ensemble perturbations

The aim of this session is to introduce the ECMWF ensemble of data assimilation (EDA). The rationale and methodology of the EDA will be illustrated, and its use in to simulate initial uncertainties in the ECMWF ensemble prediction system (ENS) will be presented.

By the end of the session you should be able to:
- know what is the ECMWF EDA
- illustrate how the EDA is used to simulate initial uncertainity in ensemble prediction
- understand the main differences between singular vectors and EDA-based perturbations | Abstract: The lectures introduce methods of ensemble verification. They cover the verification of discrete forecasts (e.g. dry/wet) and continuous scalar forecasts (e.g. temperature). Various scores such as the Brier score and the continuous ranked probability score are introduced.

After the lectures you should be able to:
- explain what a reliable probabilistic forecast is and how to measure reliability
- understand why resolution and sharpness of a probabilistic forecast matter
- compute several of the standard verification metrics used for ensemble forecasts | This lecture provides a broad overview of the role of the ocean on the predictability and prediction of weather and climate. It introduces some basic phenomena needed to to understand the time scales and nature of the ocean-atmosphere coupling. | Magdalena Balmaseda
- tcourse16_ocean.pptx

#### Roberto Buizza
- RB_2016_05_TCL2_SVs_EDA.pptx

#### Magdalena Balmaseda
- tcourse16_Initialization.pptx

#### Martin Leutbecher
- v2handout.pdf
<table>
<thead>
<tr>
<th>Time</th>
<th>Session Description</th>
<th>Presenter(s)</th>
<th>Slides</th>
</tr>
</thead>
<tbody>
<tr>
<td>10:35-11:35</td>
<td>The aim of this session is to introduce the idea of chaos. We will discuss the implications this has for numerical weather prediction. By the end of the session you should be able to:</td>
<td>Roberto Buizza</td>
<td>RB_2016_05_TCL1_sources_unc.pptx</td>
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<tr>
<td></td>
<td>• describe what limits the predictability of the atmosphere</td>
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<td>• understand the need for probabilistic forecasting</td>
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<td></td>
<td>Sarah Keeley</td>
<td>Intro_to_ChaosPres.pptx</td>
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<tr>
<td>11:45-12:45</td>
<td>The aim of this session is to introduce the main sources of uncertainty that lead to forecast errors. The weather prediction problem will be discussed, and stated in terms of an appropriate probability density function (PDF). The concept of ensemble prediction based on a finite number of integration will be introduced, and the reason why it is to be the only feasible method to predict the PDF beyond the range of linear growth will be illustrated. By the end of the session you should be able to:</td>
<td>Martin Leutbecher</td>
<td>v1handout.pdf</td>
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<tr>
<td></td>
<td>• explain which are the main sources of forecast error</td>
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<td>• illustrate why numerical prediction should be stated in probabilistic terms</td>
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<td>• describe the rationale behind ensemble prediction</td>
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<td></td>
<td>Roberto Buizza</td>
<td>RB_2016_05_TCL1_TIGGE.pptx</td>
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<td>The aim of this session is to illustrate the key characteristic of the nine operational global, medium-range ensemble systems. These are the ensembles available also within the TIGGE (Thorpex Interactive Grand Global Ensemble) project data-base. Similarity and differences in the approaches followed to simulate the sources of forecast uncertainties will be discussed, and their relevance for forecast performance will be illustrated. By the end of the session you should be able to:</td>
<td>Franco Molteni</td>
<td>TCPR_Molteni_regimes.ppt</td>
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<td></td>
<td>• illustrate the main similarities and differences of the 9 TIGGE global ensembles</td>
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<td>• link the performance differences of TIGGE ensemble to their design</td>
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<td>• describe the main differences between singular vectors and EDA-based perturbations</td>
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<td>Roberto Buizza</td>
<td>RB_2016_05_TCL1_TIGGE.pptx</td>
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<tr>
<td></td>
<td>The aim of this session is to understand the ECMWF clustering products. By the end of the session you should be able to:</td>
<td>Laura Ferranti</td>
<td>TC_clustering_2016.pdf</td>
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<tr>
<td></td>
<td>• explain how the cluster analysis works</td>
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<td>• use the ECMWF clustering products</td>
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<td></td>
<td>Laura Ferranti</td>
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<td>Martin Leutbecher</td>
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<td>13:45-14:45</td>
<td>The aim of this session is to provide a general overview of monthly forecasting at ECMWF. We will review the main sources of predictability for the sub-seasonal time scales, including the Madden Julian Oscillation, sudden stratospheric warmings (SSWs), land initial conditions and their simulation by the coupled IFS-NEMO system. The skill of the ECMWF operational monthly forecasts will also be discussed. By the end of the session you should be able to:</td>
<td>Frederic Vitart</td>
<td>TCPP_Vitart_2016_MJO.pptx</td>
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<td>• List the different sources of predictability for extended range forecasts</td>
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<td>• Describe the operational system used to produce the ECMWF monthly forecasts</td>
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<td>• Assess the shift of the monthly forecasting system</td>
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<td>Frederic Vitart</td>
<td>TCPP_Vitart_2016_MJO.pptx</td>
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<tr>
<td>14:45-15:45</td>
<td>The aim of this session is to discuss the essentials of building a numerical seasonal forecast system, as exemplified by the present prediction system at ECMWF. By the end of this lecture, you should be able to:</td>
<td>Tim Stockdale</td>
<td>tc2016_seasonal.ppt</td>
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<tr>
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<td>• explain the scientific basis of seasonal forecast systems</td>
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<td>• describe in outline ECMWF System 4 and its forecast performance</td>
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<td>• discuss the critical factors in further improving forecast systems</td>
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<tr>
<td></td>
<td>Tim Stockdale</td>
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| 2.00-3.00 | The aim of this session is to understand how we are able to provide forecasts at long time horizons given the chaotic nature of the atmosphere. After this session you should be able to:  
- describe the Lorenz idea of Predictability of the first and second kind  
- list examples of the elements of the Earth system that provide predictability on longer timescales  
- understand the type of forecast that we are able to provide beyond the deterministic limit  

Sarah Keeley  
Beyond_limit_upd.pptx | After this lecture, students will be able to:  
- explain the physical and practical motivations for using stochastic physics in an ensemble forecast  
- describe the two stochastic parameterization schemes used in the IFS ensemble, and their respective purposes  
- be able to identify the improvement in forecasting skill from the inclusion of stochastic physics.  

Sarah-Jane Lock  
StochPhys2016.pdf | Increasing observation volumes and model complexity, decreasing errors, and a growing desire for uncertainty information, all necessitate developments in our diagnostic tools. The aim of these lectures is to discuss some of these tools, the dynamical insight behind them, and the residual deficiencies that they are highlighting.  
By the end of the lectures you should be aware of:  
- Some of the key weaknesses of the ECMWF forecast system  
- Some of the diagnostic tools used to identify and understand these weaknesses  

Mark Rodwell  
20160511_TC_PR_Diags_1_02.pptx | This lecture gives an overview of ensemble and post-processing and calibration techniques. The presentation is made from the medium-range forecast perspective. The (relative) benefits of calibration and multi-model combination for medium-range forecasting are also discussed.  
By the end of this lecture, you should be able to:  
- describe a wide range of possible calibration methods for ensemble systems  
- explain which methods are suitable in which circumstances  
- discuss the merits of calibration and multi-model combination  

Tim Stockdale  
tc2016_calibration.pptx |

| 3.30-4.30 | The aim of this lecture is to discuss basic concepts behind initial perturbation techniques. After the lecture you should be able to:  
- Understand the difference between singular vectors and breeding (ETKF) vectors  
- Explain why pure random perturbations do not work  

Linus Magnusson  
training_2016_inipert1_lm.pptx | Lecture and Practice Session:  
Abstract: The lecture is a short introduction to operational hydrological ensemble prediction systems, with focus on flooding. The European Flood Awareness System (EFAS) is described. The lecture also contains a short interactive exercise in decision making under uncertainty using probabilistic forecasts as an example.  
By the end of the session you should be able to:  
- Describe the components in hydrological ensemble prediction systems (HEPS)  
- Describe the major sources of uncertainty in HEPS and how they can be reduced  
- Explain the difficulties in using probabilistic flood forecasts in decision making.  

Fredrik Wetterhall  
fred_flooding2016.pptx | Practice Session:  
You get the opportunity to experiment yourself with an ensemble prediction system for a chaotic low-dimensional dynamical system introduced by Edward Lorenz in 1995. Experiments permit to study the role of the initial condition perturbations and the representation of model uncertainties. Various metrics introduced in the ensemble verification lectures will be applied in this session.  
After the practice session, you will be able to use the toy model as an educational tool.  

Martin Leutbecher  
Linus Magnusson/Sarah Keeley |

| 4.30-5.15 | Understanding Ensembles Practical  
5.15 Poster session and ice breaker | Practical extension | Practical extension |

| 2.45pm Discussion Session in the Weather Room | The latest medium, monthly and seasonal forecasts will be discussed in terms of outlook and performance. This is a combined event with the weekly weather discussion that ECMWF staff attend. |  |  |